

B.E. (FULL-TIME) DEGREE END SEM EXAMINATIONS April/May 2012
ELECTRICAL AND ELECTRONICS ENGINEERING
VII SEMESTER (REGULATION 2004)
EE 471: DIGITAL SIGNAL PROCESSORS

Time: 3 Hours

Max. Marks: 100

Answer ALL Questions

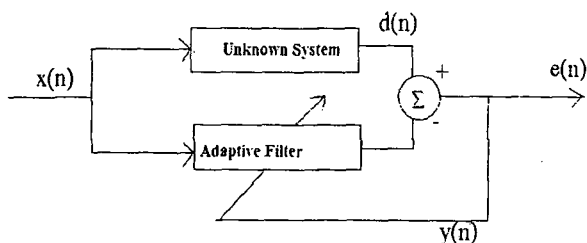
PART – A (10 x 2 = 20 Marks)

- 1 What are the components of DSP system?
- 2 What are the advantages of using programmable DSP processors? How are DSP processors compared with application-specific integrated circuits (ASICs), general-purpose micro processors, and micro controllers.
- 3 Perform Binary Multiplication : $2.4 * -12.16$
- 4 Explain bit reversal addressing mode.
- 5 What are the various interrupt types supported in 5X processor
- 6 Give a brief account of the load/store instructions of 5X processor
- 7 List the data buses and address buses in 'C3X processor?
- 8 List the number of execution of pipeline stages used in C3x and C67x processors
- 9 Show the generic block diagram of Adaptive filter
- 10 Briefly Investigate the effects of quantizing adaptive filters

PART – B (5 x 16 = 80 Marks)

- 11 a (i) Show the memory map of TMS320c5510 (4)
(ii) What is the Software and Hardware development tools required to design a new DSP based application. Explain the each component. (12)
 - 12 a (i) Discuss and draw the Signal flow diagram of FIR and IIR filter. Obtain its transfer function in z domain. (16)
- OR**
- b (i) Write the differences between fixed point and floating point Digital signal processor (8)
(ii) Show the interfacing diagram between DSP Processor and host device (8)
 - 13 a (i) Draw the internal architecture diagram of 5X and indicate the various blocks. (8)
(ii) What are instructions of C5X which are used for block transfer (8)
- OR**
- b (i) Write a C5X program to generate a Triangular wave (8)
(ii) Explain how the FSK signal may be demodulated using a C5X program (8)

- 14 a (i) List the various data formats available in 'C3X processor (8)
 (ii) Show the Fixed point implementation of IIR Filter (8)
OR
- b (i) Describe the two basic techniques which can be used for generating random numbers (16)
- 15 a (i) List and describe the various adaptive algorithm (16)
OR
- b (i) Discuss the effects of choosing filter L for an adaptive FIR filter with the LMS algorithm in terms of stability, convergence rate and excess MSE of the algorithm. (8)
- (ii) As shown in the figure below, if the unknown system is given as $P(z)=0.75+0.5z^{-1}-0.6z^{-2}$, the adaptive filter is $W(z)=w_0+w_1z^{-1}+w_2z^{-2}$, and excitation signal $x(n)$ is a zero mean white noise with variance 1, find the following: (8)
- The R matrix and p vector
 - The optimum solution of adaptive filter w
 - The minimum MSE after the convergence of the adaptive filter



System Identification using adaptive filters